

Hojune Kim

B.S. Student in Aerospace Engineering,
Seoul National University, Seoul, South Korea
+82-10-5424-7269 — hojjunekim@snu.ac.kr
[Personal Website](#)

RESEARCH INTERESTS

SLAM, Sensor Fusion, 3D Computer Vision, Nonlinear Control

EDUCATION

Seoul National University, South Korea 2019 - Present

B.S. in Aerospace Engineering

GPA: 4.07/4.30 (Major: 4.24/4.30)

- Major Coursework: Decision Making for Autonomous Aerospace Systems, Principles of Flight Vehicle Control, Aerospace Sensor Systems, Introduction to Computer Vision

Gyeonggi Science High School for the Gifted, South Korea 2016 - 2019

RESEARCH EXPERIENCE

Robust Perception and Mobile Robotics Lab, SNU Jan 2023 - May 2023

Research Intern, Advisor: Prof. Ayoung Kim

Topic: Modeling Multimodal Sensor system for Long-term Localization

- 3D printed the handheld system for 3D LiDAR, RGB-D Camera, Thermal Camera, IMU, GNSS sensor fusion
- Applying Thermal-LiDAR direct odometry SLAM(DSO) under ROS1
- Carry out Thermal-LiDAR calibration methods

Satellite Geophysics Lab, Seoul National University Aug 2020 - Jun 2021

Research Intern, Advisor: Prof. Duk-jin Kim

Topic: Real-time flood monitoring system by water segmentation using Sentinel-1 satellite SAR image

- Trained flood segmentation model based on DeepLab V3+ with SAR image
- Automated a system of train data achieve and labeling from land cover map

TECHNICAL EXPERIENCE

SNU ZERO, VDCL Lab. SNU Mar 2021 - Oct 2021

Sensor Fusion team, Autonomous driving algorithm academic club

- Autonomous driving algorithm research club
- Used Velodyne lidar, GPS, IMU etc., ADAS sensors under ROS1
- Sensor fusion to estimate car's perception and develop the autonomous driving algorithm

AI Tech Play, College of Engineering in SNU Feb 2021 - Aug 2021

Hardware Team Leader, AI education sharing Organization

- Planned and held the AI RC-car competition for children nationwide (over 200 students participated)
- Designed and manufactured RC-car with rgb-d camera, lidar and jetson board
- Applied autonomous driving skills in RC-car under ROS2

TECHNICAL SKILLS	Languages: Python, C/C++, javascript Frameworks: ROS1/2, OpenCV, Tensorflow Tools: Matlab, SolidWorks, Bash, QGIS	
AWARDS & HONORS	Kwanjeong Undergraduate Scholarship <i>Full coverage of junior and senior tuition & stipend</i>	Mar 2021
	Gold Prize, International Student Car Competition <i>Autonomous driving sector</i>	Oct 2021
	Excellence Prize, Ministry of Defense Startup Competition <i>Minister of National Defense Award</i>	Dec 2022
	Final Selected, Star-Exploration Startup Support Project <i>Korea Aerospace Research Institute(KARI)</i>	Feb 2021
	Certificate of Appreciation(AI Tech Play) <i>Dean, College of Engineering in Seoul National University</i>	Jun 2021
	Bronze Prize, Human Tech Paper Award <i>Samsung Electronics, High School Students section</i>	Aug 2018
TEACHING EXPERIENCE	Teaching Assistant, at SNU <i>Basic of Robot Programming and Mechanical System Design</i>	Spring 2023
	Teaching Tutor, at SNU <i>Dynamics and Engineering Mathematics</i>	Fall 2023
PROJECTS	Autonomous Flight Control in Quadrotor system Path planning via bézier curve, auto landing in simulation and real flight	2023
	Fault Tolerant Control of Quadrotor Design Controller via Feedback Linearization, Sliding Mode and Backstepping	2023
	Display a Virtual Object on My Desk Feature matching and 3D Reconstruction with images on SE(3)	2023
	Web Scrapper Extension for blog and community editor Develop chrome extension under vanilla JS	2022
PATENT	Parking Location Tracking System, KR102291377B1 • H.J. Kim, T.I. Kim, J.H. Na, J.Y. Lee, S.H. Jeong	2021
EXTRA CURRICULAR	CH-47 Helicopter Flight Attendant, ROKA Put on the forest fire extinguish mission(Uljin, Young-dok)	Aug 2021 - Feb 2023
	Cube-Satellite Club, GNSS Lab. SNU Studied MFC programming and signal processing with Atmega128	May 2020 - Jun 2021
	Science Volunteer Corps, College of Natural Sciences in SNU	Jul 2019